

## **Announcements 4/1/10**

Midterm 2 information handout has schedule of SA sessions and review for Saturday's exam. (April Fool — yes, the exam is Thursday 4/8 :-))

Friday afternoon office hours: 1:30 – 3 (no junior lab)

Graded homework and self-tests available in lab, then outside my office after today's lab

## Key ideas from last time

Field of a loop of current on its axis:

$$B(x,0,0) = \frac{\mu_0 I a^2}{2(x^2 + a^2)^{3/2}} \quad \text{factor of 2 in denominator!}$$

$x$  = distance along axis

$a$  = loop radius

For  $x \gg a$ ,  $B(x,0,0) \approx \frac{\mu_0 I a^2}{2x^3}$

Current loop is a *dipole*:  $B \propto 1/x^3$ , overall field has dipole shape

Define magnetic dipole moment:

$$\vec{\mu} = I\pi a^2 \text{ in direction of } \vec{B} \text{ on axis} \quad \text{factor of } \pi!$$

$$\text{allows us to write } B(x,0,0) \approx \frac{\mu_0 \mu}{2\pi x^3} \quad \text{factor of } 2\pi!$$

BTW: Earth's magnetic field is also a dipole field and is thought to come from a loop of current *inside* Earth— but explaining *why* there is a current will have to wait for next week!

Torque on dipoles in external magnetic field (NOT  $B_{\text{dipole}}$ ):

rotates dipole so that  $\vec{\mu}$  aligns with (parallel to)  $\vec{B}$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

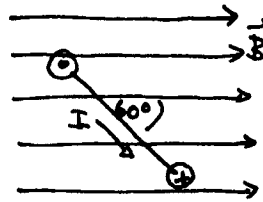
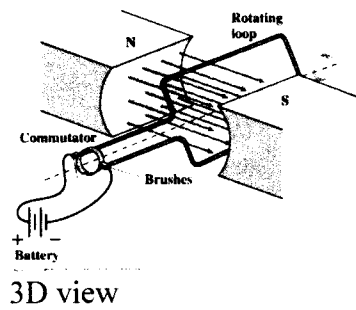
magnitude:  $\tau = \mu_{\perp} B = \mu B \sin \theta$

direction:

## Problems for class 4/1/10

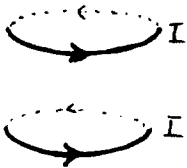
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Suppose the electric motor in a Prius hybrid car has a rectangular coil 10 cm x 20 cm with 1000 turns. The motor operates at 500 V and has a 50 kW power output. The magnetic field produced by the magnets in the motor is 0.050 T. What is the torque on the motor coil when it is in the orientation shown?



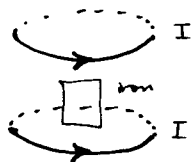
side view

What is the direction of the force on the lower current loop due to the upper current loop?



Suppose each magnetic particle in a bacterium is a sphere 50 nm in diameter made of material that has a magnetic moment per volume of  $M = 5 \times 10^5$  A/m. What is the energy required to rotate one such particle from having its dipole moment parallel to the Earth's magnetic field to antiparallel to the Earth's magnetic field? (Assume the strength of the Earth's magnetic field is  $60 \mu\text{T}$ .) How does this compare to the thermal energy  $k_B T$  at room temperature, which is  $4.1 \times 10^{-21}$  J? Why do you suppose bacteria typically have 10 to 20 of these particles?

A piece of iron is magnetized by placing it between two current loops as shown. What is the direction of the magnetic moment of the iron?



J.J.

4/1/2010

(1) Review RH rules

(2)  $\vec{\mu}$  of any current loop:  $\vec{\mu} = N I \vec{A}_{\text{loop}}$

(3) Torques on magnetic dipoles: electric motor

(4) Energy of dipoles in field:

magnetic sensing

NMR if time

(5) Magnets as dipoles

### Right-hand rules

(1) Direction of cross product:  $\vec{A} \times \vec{B}$

use: RH fingers in direction of  $\vec{A}$

hold hand so you can curl fingers to  $\vec{B}$

cross product is in direction of thumb

This applies to  $\vec{F} = q \vec{v} \times \vec{B}$  (remember to allow for  $q$  possibly being negative)

and  $\vec{F} = I \vec{L} \times \vec{B}$

and  $\vec{\tau} = \vec{\mu} \times \vec{B}$  (which comes from)

(2) Direction of  $\vec{B}$  of current:

$\vec{B}$  forms loops around  $I$

point thumb along current; RH fingers curl in direction of  $\vec{B}$

(3) (Not really a new rule but a shortcut)

$\vec{\mu}$  of current loop is defined to point in direction of  $\vec{B}$  on axis of current loop — can find this by how  $\vec{B}$  loops around current

Also: if you curl RH fingers in direction of current, thumb points in direction of  $\vec{B}$  on axis of  $\vec{\mu}$

## Magnetic dipole moment of any current loop or coil

For single circular loop we defined

$$\vec{\mu} = I\pi a^2 \text{ in direction of } \vec{B} \text{ on axis}$$

Can write in terms of loop area:

$$\vec{\mu} = I\vec{A}_{\text{loop}}$$

$$\vec{A}_{\text{loop}}: \begin{cases} \text{magnitude} = \text{area of loop} \\ \text{direction} = \text{same direction as } \vec{B} \text{ on axis} \end{cases}$$

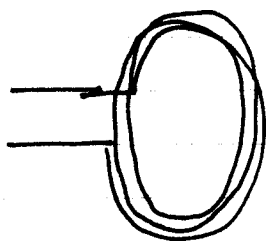
[in general: next week you'll work with a vector area in lab - vector area is always  $\perp$  to the plane in which the surface exists] [for magnetism we pick it to be in the same direction as  $\vec{B}$  on axis]

Turns out that in general, any shape loop,

$$\vec{\mu} = I\vec{A}_{\text{loop}}$$

Can make a coil with multiple "turns": wrap wire around multiple times

Example: 3 turn coil



Three turns  $\rightarrow$  coil has 3x the  $\vec{B}$  of just one loop

in external  $\vec{B}$ , coil feels 3x the torque of just one loop

$$\Rightarrow \vec{\mu} = N I \vec{A}_{\text{loop}} \text{ where } N = \# \text{ of turns}$$

## Sample problem: electric motor

How do motors work:

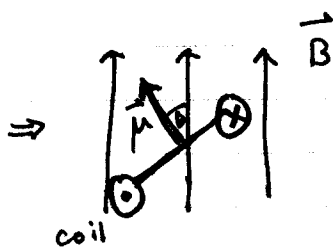
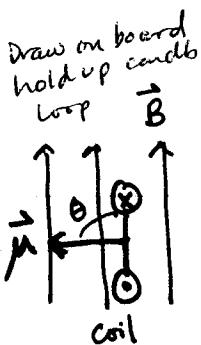
motor needs to take electric energy from a current and use it to turn something — i.e. ~~motor~~ <sup>axle of car</sup> ~~of~~ pass current through motor coil — it feels a torque ~~due~~ due to magnets mounted around it

Start with  $\vec{\mu}_{\text{coil}} \perp$  to  $\vec{B}$ : it feels torque

$$\vec{\tau} = \vec{\mu}_{\text{coil}} \times \vec{B} = \mu_{\text{coil}} B \sin \theta \text{ in direction from cross prod}$$

Direction of torque: if you use the Cross product rule get a direction along the axis of rotation

I think it makes more sense for our purposes to indicate the way the coil rotates: for example, viewed like this the coil rotates clockwise



Magnitude of torque is

$$\tau = \mu_{\perp} B = \mu B \sin \theta$$

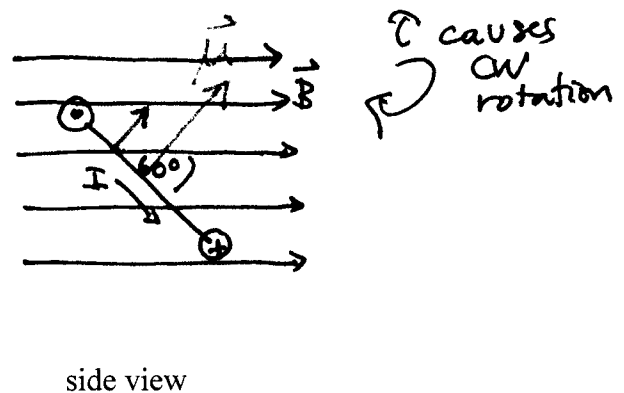
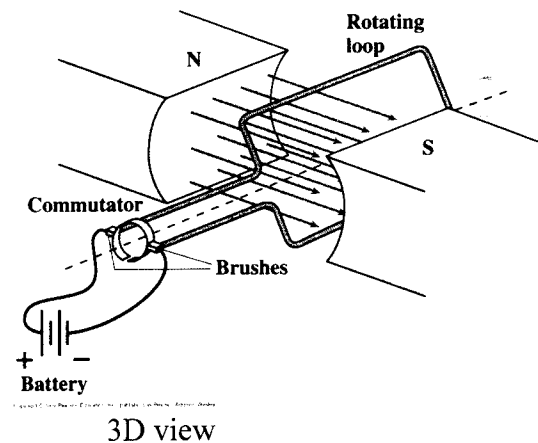
where  $\theta$  = angle between  $\mu$  and  $B$

Motors ~~must~~ use a special trick so that torque keeps them turning in same direction all the time instead of reversing: a way to switch current direction

Easiest to see on a 3D object — we'll look at this in lab in 2 weeks

Ask:  
direction  
of torque  
once just  
past parallel?

Suppose the electric motor in a Prius has a rectangular coil 10 cm x 20 cm with 1000 turns. The motor operates at 500 V and has a 50 kW power output. The magnetic field produced by the magnets in the motor is 0.050 T. What is the torque on the motor coil when it is in the orientation shown?



Principle:  $\vec{\tau} = \vec{\mu} \times \vec{B}$  magnitude  $\tau = \mu B \sin \theta$   
 Need  $\mu$ ,  $\theta \Rightarrow \theta = 30^\circ$  between  $\vec{\mu}$  and  $\vec{B}$

$\mu = N I A_{\text{loop}}$  need  $I$

$$\text{Power} = I V \Rightarrow I = \frac{\text{Power}}{V}$$

$$\mu = (1000) (100 \text{ A}) (2.0 \times 10^{-2} \text{ m}^2) = 2000 \text{ A m}^2$$

$$\Rightarrow \tau = 50 \text{ N} \cdot \text{m}$$

Direction: causes loop to rotate CW in side view

Prior problem

Goal: Need to find the torque on the motor

Principle: Current loop experiences torque  $\vec{\tau} = \vec{\mu} \times \vec{B}$  in magnetic field  
Need to find  $\vec{\mu}$ , given loop geometry and motor power and voltage

$$\vec{\mu}_{\text{loop}} = N I \vec{A}_{\text{loop}} \quad \text{need current}$$

To find current: recall power =  $I V$  in general

$$\text{so } I_{\text{motor}} = \frac{P_{\text{motor}}}{V_{\text{motor}}} = \frac{50 \times 10^3 \text{ W}}{500 \text{ V}} = 100 \text{ A (a lot!)}$$

$$\text{Area of loop: } A = \frac{1}{2} \times 20 \text{ cm} \times 20 \text{ cm} = 200 \text{ cm}^2 = 2.0 \times 10^{-2} \text{ m}^2$$

$$\Rightarrow \mu = N I A_{\text{loop}} = (2000 \text{ turns})(100 \text{ A})(2.0 \times 10^{-2} \text{ m}^2) = 4000 \text{ A} \cdot \text{m}^2$$

Now use  $\tau = \mu B \sin \theta$  with angle <sup>shown</sup> as  $30^\circ$  — this is the angle between  $\vec{\mu}$  and  $\vec{B}$  so it's

$$\Rightarrow \tau = \left( \frac{4000}{50} \text{ A} \cdot \text{m}^2 \right) (50 \times 10^{-3} \text{ T}) \sin 30^\circ \quad \text{the right one}$$

$$\tau = 10 \text{ N} \cdot \text{m}$$

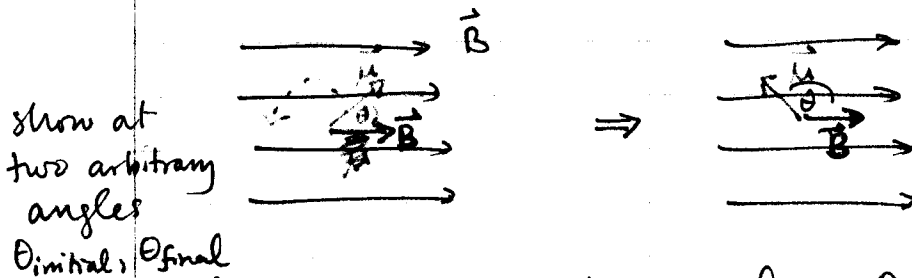
What if you want more torque? Increase  $N$  (harder to increase  $I$  or  $B$ )



## Energy of dipoles in $\vec{B}$

To move dipole away from  $\vec{\mu} \parallel \vec{B}$  requires pushing on it - must do work and therefore ~~store~~ <sup>increase potential</sup> energy

(Draw  $\vec{B}$  on board, show arrow rotating)



To find work required to go from  $\theta_{\text{initial}}$  to  $\theta_{\text{final}}$ :

$$W = \int_{\theta_{\text{initial}}}^{\theta_{\text{final}}} \tau d\theta = \int_{\theta_{\text{initial}}}^{\theta_{\text{final}}} \mu B \sin \theta d\theta = -\mu B \cos \theta \Big|_{\theta_{\text{initial}}}^{\theta_{\text{final}}}$$

$$\text{so } \Delta U = -\mu B (\cos \theta_{\text{final}} - \cos \theta_{\text{initial}})$$

~~Book chooses~~

Most relevant energy difference: from parallel ( $0^\circ$ ) to anti ( $180^\circ$ )

$$\Delta U = -\mu B (\cos 180^\circ - \cos 0^\circ) = 2\mu B$$

antiparallel is higher in energy by  $2\mu B$   
this much energy is required to reverse  $\vec{\mu}$

[ Your book chooses reference to be  $\theta_{\text{initial}} = 90^\circ$  and then  $U_{\theta_{\text{final}}} = -\mu B \cos \theta_{\text{final}} = -\vec{\mu} \cdot \vec{B}$  in final position ]   
 from its lowest energy orientation

— Exam material stops here —

Magnetic materials: How does all this relate to what we colloquially call "magnets"?

What you may have used or played around with as a kid: a chunk of material that picks up paper clips (but not copper pennies) and sticks to your refrigerator (but not aluminum foil)


Mazur  
Fig 31.3

If you have two of them, you find that a magnet has two ends, which we call "north" and "south" poles, and that like poles repel while unlike poles attract — very strongly, in fact?

Where does the name north/south come from? Compass is a sliver of magnet ~~set~~ set on a ~~base~~ <sup>pivot</sup> so it can rotate — observed long ago that it turns so that its "north" end goes toward magnetic north.

Mazur  
Fig 31.2

In fact this rotation happens b/c the compass needle is a magnetic dipole w/ its  $\vec{\mu}$  from S to N: feels a torque from Earth's  $\vec{B}$ , rotates so it aligns parallel to  $\vec{B}_{\text{Earth}}$  (which points from the south to the north).



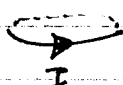
Any chunk of magnet turns out to be a magnetic dipole — its field is the same form as a current loop (Fig 32.8)

Figs 31.7-8

Might think N pole and S pole are like  $\oplus$  and  $\ominus$

**BUT** if you cut a magnet in half, get two new dipoles each with S and N — all the way to the atomic level!

So can think interchangeably about magnets, current loops, & dipoles:

$$\begin{array}{|c|} \hline \text{N} \\ \hline \text{S} \\ \hline \end{array} = \uparrow \vec{\mu} = \text{current loop}$$


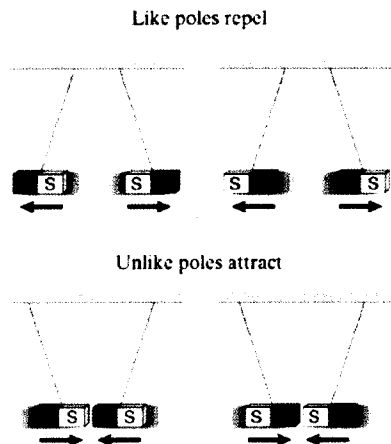


Figure 31.3 Interactions between magnetic poles.

Magnets have two distinct "poles"  
"north" and "south"

like poles repel  
opposite poles attract

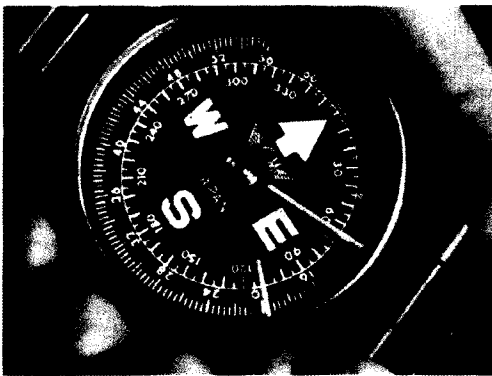
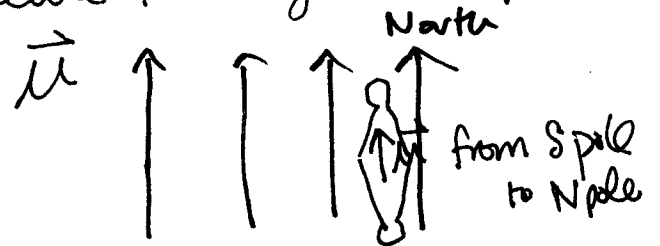


Figure 31.2 The needle of a compass is a small magnet that is free to rotate. When the compass is held horizontally, the needle aligns itself in such a way as to point from South to North.

Poles are named this way  
because N end of magnet  
turns toward geomagnetic  
north (and likewise S)

Needle is magnetic dipole



torque aligns  $\vec{\mu}_{\text{compass}}$  to  $\vec{B}_{\text{Earth}}$

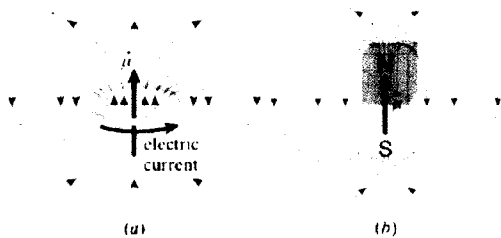
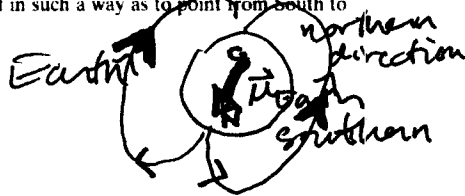
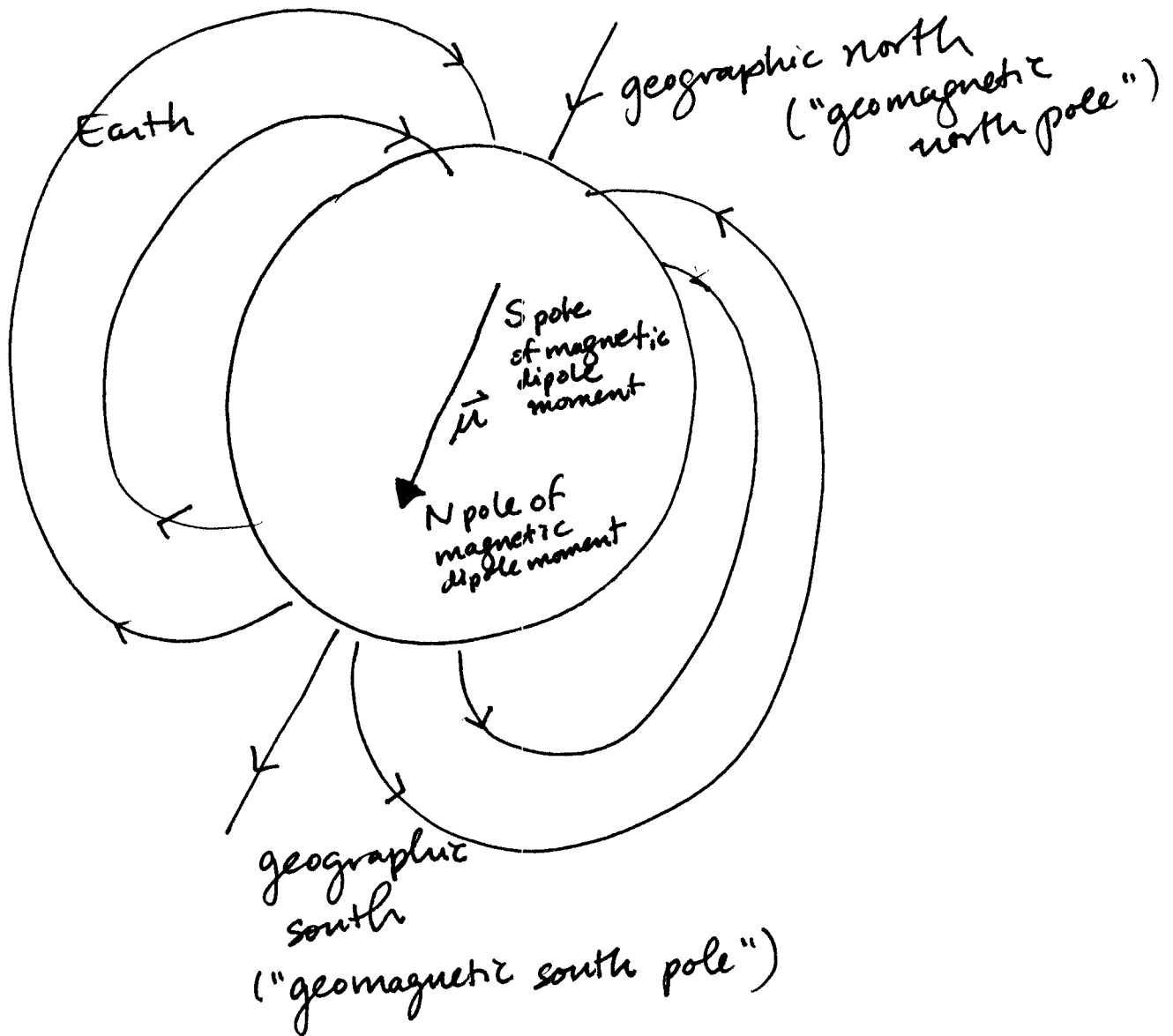
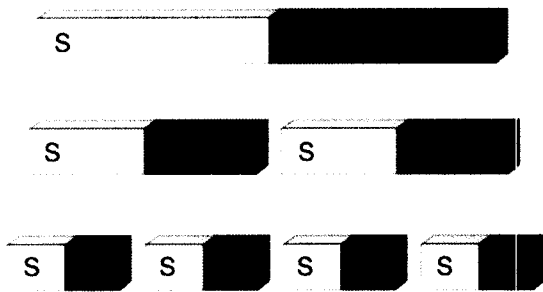


Figure 32.8 The magnetic dipole moment vector  $\vec{\mu}$  points along the axis of a (a) current loop and (b) bar magnet, in the same direction as the magnetic field.

"magnets" are dipoles

Clearer picture of Earth's field and dipole moment





**Figure 31.7** When a magnet is cut in two, each piece retains both a N and S pole.

Does this mean

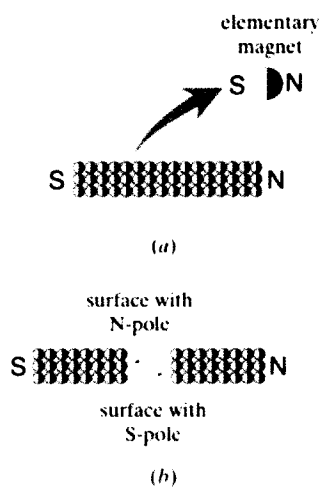
$$N = \oplus$$

$$S = \ominus ?$$

No — if break in half  $\rightarrow$  more dipoles

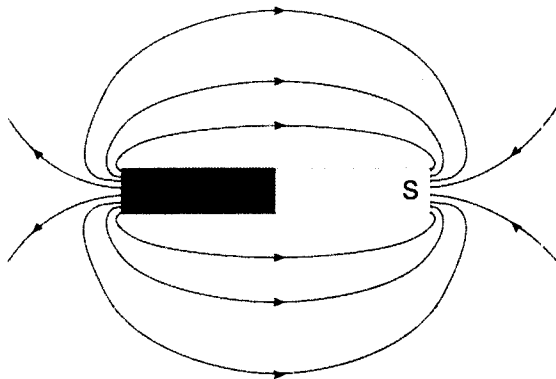
B/C magnetism comes from loop of current

= "Spin" of  $e^-$ , nuclei



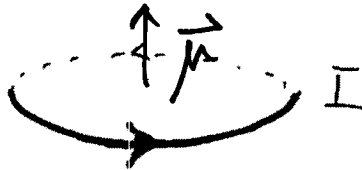
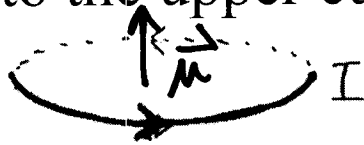
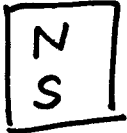
**Figure 31.8** (a) In a magnetized piece of material, all the elementary magnets are aligned. (b) Cutting the piece in two exposes two new poles.

$$\begin{array}{|c|} \hline N \uparrow \\ \hline S \downarrow \\ \hline \end{array} \vec{\mu} = \text{loop of current } I = \vec{\mu} \uparrow$$



**Figure 31.13** Magnetic field line pattern surrounding a bar magnet.

What is the direction of the force on the lower current loop due to the upper current loop?



can use  $I\vec{L} \times \vec{B}$   
also

$\vec{B}$  top into page  
on lower loop  
at front

→  $\vec{F}_{up}$

1. Left

2. Right

3. Up

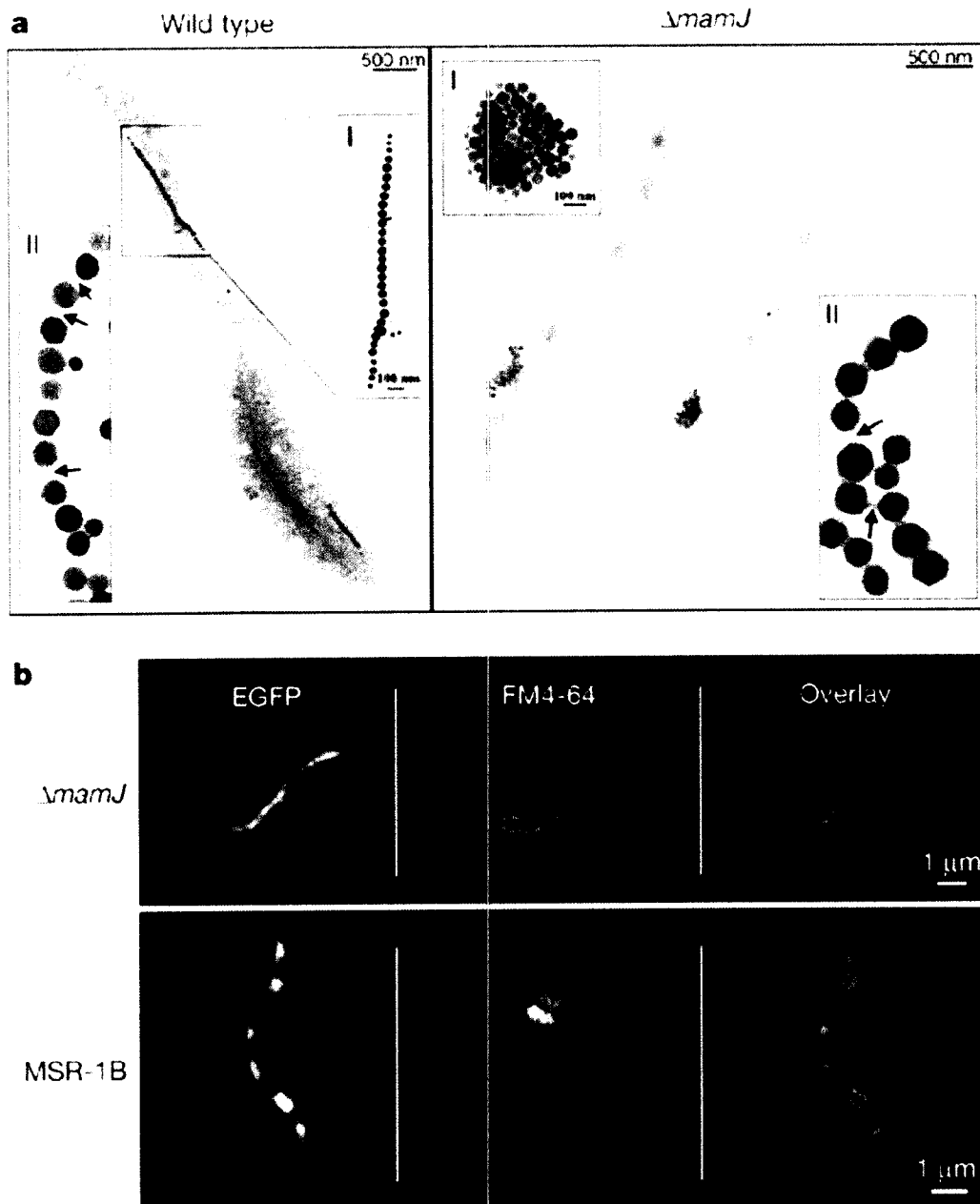
4. Down

5. Into page

6. Out of page

7. There is zero net force.

From Nature 440, 110–114 (2 March 2006), “An acidic protein aligns magnetosomes along a filamentous structure in magnetotactic bacteria,”  
by André Scheffé, Manuela Gruska, Damien Faivre, Alexandros Linaroudis, Jürgen M. Plitzko and Dirk Schüler



Suppose each magnetic particle in a bacterium is a sphere  $50 \text{ nm}$   $\times 10^{-9} \text{ m}$  in diameter made of material that has a magnetic moment per volume of  $M = 5 \times 10^5 \text{ A/m}$ . What is the energy required to rotate one such particle from having its dipole moment parallel to the Earth's magnetic field to antiparallel to the Earth's magnetic field? (Assume the strength of the Earth's magnetic field is  $60 \mu\text{T}$ .) How does this compare to the thermal energy  $k_B T$  at room temperature, which is  $4.1 \times 10^{-21} \text{ J}$ ? Why do you suppose bacteria typically have 10 to 20 of these particles?

$$\Delta U_{\text{to flip}} = 2\mu B$$

$$\mu = M \text{ vol} = M \frac{4}{3}\pi \left(\frac{d}{2}\right)^3 = 3 \times 10^{-17} \text{ A m}^2$$

$$B_{\text{earth}} = 60 \times 10^{-6} \text{ T}$$

$$\rightarrow \Delta U_{\text{to flip}} = 3.6 \times 10^{-21} \text{ J}$$

$$k_B T \text{ at room } T = 4.1 \times 10^{-21} \text{ J}$$

$$\Delta U_{\text{to flip a chain of 10}} = 10(3.6 \times 10^{-21} \text{ J}) = 3.6 \times 10^{-20} \text{ J}$$



Applications:  
mag sensing  
NMR

(could save for after  
ferro/para)

7

## Magnetic sensing/navigation

many kinds of creatures use the torque of Earth's  $\vec{B}$  on magnetic particles to orient themselves — some for migration, some for other navigational purposes

(ants & other insects, fish) (birds may be more complex)

### Simplest: magnetotactic bacteria

stream/pond dwellers

anaerobic — need to find their way to the bottom

of the water for food and to avoid oxygen  
in N hemisphere,  $\vec{B}$  of earth points mostly down —  
so can follow Earth's field to go down

(Why not use gravity? Not strong enough — bacteria are not significantly denser than the water surrounding them)

Bacteria contain a chain of 10-20 tiny magnetic particles each  $\sim 50$  nm in diameter

$$\mu \approx 3 \times 10^{-17} \text{ A} \cdot \text{m}^2 \text{ for each}$$

Is torque strong enough to keep bacteria following  $\vec{B}$  earth?

Difference in energy between aligned & anti-aligned:

$$\Delta U = 2\mu B = 2(3 \times 10^{-17} \text{ A} \cdot \text{m}^2)(6 \times 10^{-6} \text{ T}) = 3.6 \times 10^{-21} \text{ J}$$

Ten particles requires 10x energy:  $\Delta U = 3.6 \times 10^{-20} \text{ J}$

Room temperature: thermal energy is  $4.1 \times 10^{-21} \text{ J}$  —  
so 10 particles will keep bacteria pointing down —  
not enough thermal energy to push them around.

(How do they know this is right? Take bacteria to S hemisphere where  $\vec{B}$  points up — bacteria go to top & die.)

DIP  
NEEDLE  
DEMO

$$\mu = M \cdot \text{vol} \\ = M \cdot \frac{4\pi}{3} \left(\frac{d}{2}\right)^3$$

Do energy  
here

Stopped here  
12:30

CT?